Single-Velocity, Multi-Component Turbulent Transport Models for Interfacial Instability-Driven Flows



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Outline of presentation



- Motivation
 - The need for turbulent transport and mixing models
 - Single- vs. multiple-velocity, multi-component fluid formulations
- Derivation of the Favre-Reynolds averaged single-velocity equations
- Two-equation turbulence models
 - The general K-Z model
 - The K- ϵ model
 - Derivation of consistent K-I, K- ω , and K- τ models
- Work in progress: a priori model tests
 - Determination of model coefficients from experimental data
 - Determination of model coefficients from simulation data
- Conclusions

An *averaged* description of turbulent transport and mixing is needed due to the very wide range of spatio-temporal scales in turbulent mixing layers



- Direct numerical simulation (DNS) cannot attain parameter regimes of interest for astrophysical and inertial confinement fusion (ICF) applications
- Large-eddy simulation (LES) is not yet sufficiently developed
- Interim solution: turbulent transport and mixing models, which have similarities with LES
- Transport models are based on closing terms in the density-weighted averaged equations
 - Reynolds stress tensor
 - Density and energy flux
- These quantities are modeled using an eddy viscosity approximation



Striking similarities exist between hydrodynamic instabilities in (a) inertial confinement fusion capsule implosions and (b) core-collapse supernova explosions. [Image (a) is from Sakagami and Nishihara, *Physics of Fluids B* 2, 2715 (1990); image (b) is from Hachisu et al., *Astrophysical Journal* 368, L27 (1991).]

ICF

supernova

Single-velocity formulations of multicomponent flow are significantly less complex than multiple-velocity formulations



- Single-velocity, multi-component fluid formulations:
 - Equations systematically derived from reacting flow theory
 - Equations have nearly the same form as the single-fluid, compressible fluid dynamics equations
 - Additional fluxes involving a diffusion velocity are present
 - The diffusion velocity is obtained, and these fluxes are expressed in terms of a mass diffusion flux
- Multiple-velocity, multi-component fluid formulations:
 - Require multiple advection terms equal to number of fluids
 - Require fluid dynamic fields for every fluid, so the number of equations to model and solve is large
 - Require phenomenological modeling of interfacial source terms arising from interfacial averaging: drag, added mass terms, etc.

The derivation of the single-velocity equations begins with the full, *N*-fluid equations expressing mass, momentum, and energy conservation



• In compact form, these equations are (*r* labels each fluid):

$$\frac{\partial}{\partial t}(\rho^r \phi^r_{\alpha}) + \frac{\partial J^r_{\alpha\beta}[\phi^r]}{\partial x_{\beta}} = F^r_{\alpha} + S^r_{\alpha}$$

- where the fields, fluxes, forces, and sources are



These fields are defined so that summing appropriate expressions over each fluids recovers the non-reacting, single-fluid equations



- The quantities ρ^{r} , v_{α}^{r} , U^{r} , ϕ^{r} , $\Phi_{\alpha}^{rad,r}$, Φ' , g_{α} , R^{r} , and H^{r} are the density, velocity, internal energy, scalar, radiative flux, scalar flux, acceleration, reaction rate, and heat of formation
- The pressure, viscous stress tensor, and total energy are

$$p^{r} = p^{r}(\rho^{r}, U^{r})$$

$$\sigma_{\alpha\beta}^{r} \equiv \mu^{r} \left(\frac{\partial v_{\alpha}^{r}}{\partial x^{\beta}} + \frac{\partial v_{\beta}^{r}}{\partial x^{\alpha}} \right) + \left(\xi^{r} - \frac{2\mu^{r}}{d} \right) \delta_{\alpha\beta} \frac{\partial v_{\gamma}^{r}}{\partial x_{\gamma}}$$

$$e^{r} = \frac{v_{\gamma}^{2}}{2} + U^{r} + \rho m^{r} H^{r} - \mathbf{g} \cdot \mathbf{x}$$

Consistency with the single-fluid equations is obtained with the constraints

$$\sum_{r=1}^{N} \rho^r \phi_{\alpha}^r = \rho \phi_{\alpha} , \quad \sum_{r=1}^{N} J_{\alpha\beta}^r = J_{\alpha\beta}$$
$$\sum_{r=1}^{N} F_{\alpha}^r = F_{\alpha} , \quad \sum_{r=1}^{N} S_{\alpha}^r = S_{\alpha}$$
$$\sum_{r=1}^{N} R^r = 0 , \quad \sum_{r=1}^{N} \phi_{\alpha}^r R^r = 0$$

The single-velocity equations are obtained by decomposing the velocity into a mean velocity plus a diffusion velocity

Introduce the local mass fraction of fluid r

$$m^{r}(\mathbf{x},t) \equiv \frac{\rho^{r}}{\rho}$$
, $\sum_{r=1}^{N} m^{r}(\mathbf{x},t) = 1$

• Write the velocity of fluid *r* as

$$\mathbf{v}^r = \mathbf{v} + \mathbf{V}^r$$
, $\mathbf{v} \equiv \sum_{r=1}^N m^r \mathbf{v}^r$

where V^r is the diffusion velocity, which expresses the molecular transport caused by the concentration gradient in fluid r

• The identity

$$\sum_{r=1}^N m^r \mathbf{V}^r = \mathbf{0}$$

is central to the derivation of the single-velocity equations



The single-velocity equations are a consequence of the previous identities

 Substituting the velocity decomposition into the multi-component equations, summing, and using the previous identities gives the single-velocity equations

$$\frac{\partial}{\partial t}(\rho\phi_{\alpha}) + \frac{\partial J_{\alpha\beta}}{\partial x_{\beta}} = F_{\alpha} + S_{\alpha}$$

• The fields and fluxes are

$$\rho \phi_{\alpha} = \begin{pmatrix} \rho \\ \rho v_{\alpha} \\ \rho e \\ \rho \phi \end{pmatrix} \qquad J_{\alpha\beta} = \begin{pmatrix} \rho v_{\beta} \\ \rho v_{\alpha} v_{\beta} + p \delta_{\alpha\beta} - \sigma_{\alpha\beta} \\ \rho e + p v_{\beta} - v_{\alpha} \sigma_{\alpha\beta} + \Phi_{\beta}^{rad} \\ \rho \phi v_{\beta} + \Phi_{\beta}^{\phi} \end{pmatrix} + \begin{pmatrix} 0 \\ -\sigma_{\alpha\beta}^{D} \\ J_{\beta}^{e} \\ J_{\beta}^{\phi} \end{pmatrix}$$

where the last term in $J_{\alpha\beta}$ depends on the diffusion velocity and must be modeled



The forces, sources, and other quantities are defined as follows



• The forces and sources are



• The total density, pressure, radiative flux, viscous stress tensor, dynamic viscosity, and bulk viscosity are

$$\begin{split} \rho &\equiv \sum_{r=1}^{N} \rho^{r} \qquad p \equiv \sum_{r=1}^{N} p^{r} (\rho^{r}, U^{r}) \qquad \Phi_{\alpha}^{\mathrm{rad}} \equiv \sum_{r=1}^{N} \Phi_{\alpha}^{\mathrm{rad}, r} \\ \sigma_{\alpha\beta} &\equiv \mu \Big(\frac{\partial v_{\alpha}}{\partial x^{\beta}} + \frac{\partial v_{\beta}}{\partial x^{\alpha}} \Big) + \Big(\xi - \frac{2\mu}{d} \Big) \delta_{\alpha\beta} \frac{\partial v_{\gamma}}{\partial x_{\gamma}} \\ &+ \sum_{r=1}^{N} \mu^{r} \Big(\frac{\partial V_{\alpha}^{r}}{\partial x^{\beta}} + \frac{\partial V_{\beta}^{r}}{\partial x^{\alpha}} \Big) + \Big(\xi^{r} - \frac{2\mu^{r}}{d} \Big) \delta_{\alpha\beta} \frac{\partial V_{\gamma}^{r}}{\partial x_{\gamma}} \\ \mu &\equiv \sum_{r=1}^{N} \mu^{r} \quad , \quad \xi \equiv \sum_{r=1}^{N} \xi^{r} \end{split}$$

The diffusive fluxes are defined as follows

• The multi-component viscous diffusion stress tensor is

$$\sigma^{D}_{\alpha\beta} \equiv -\rho \sum_{r=1}^{N} m^{r} V^{r}_{\alpha} V$$

• The diffusive energy flux is

$$J^e_{\alpha} \equiv \rho \sum_{r=1}^N m^r e^r V^r_{\alpha}$$

• The diffusive scalar flux is

$$J^{\phi}_{\alpha} \equiv \rho \sum_{r=1}^{N} m^{r} \phi^{r} V^{r}_{\alpha}$$



The averaged equations are obtained by introducing the Favre-Reynolds decompositions and averaging

• The Favre-Reynolds decompositions are

$$\phi_{\alpha}^{r}(\mathbf{x},t) = \widetilde{\phi}_{\alpha}^{r}(\mathbf{x},t) + \phi_{\alpha}^{r}(\mathbf{x},t)^{\prime\prime}$$

 $\rho^{r}(\mathbf{x},t) = \overline{\rho}^{r}(\mathbf{x},t) + \rho^{r}(\mathbf{x},t)' \qquad p^{r}(\mathbf{x},t) = \overline{p}^{r}(\mathbf{x},t) + p^{r}(\mathbf{x},t)'$

• The Favre average is

$$\widetilde{\phi}_{\alpha} \equiv \frac{\overline{\rho \phi_{\alpha}}}{\overline{\rho}}$$

• The Favre-averaged multi-component fluid dynamics equations are

$$\frac{\partial}{\partial t}(\overline{\rho}\,\overline{\phi}_{\alpha})+\frac{\partial\overline{J}_{\alpha\beta}}{\partial x_{\beta}}=\overline{F}_{\alpha}+\overline{S}_{\alpha}$$



The Favre-averaged fields and fluxes are defined as follows

• The fields and fluxes are

$$\overline{\rho}\,\overline{\phi}_{\alpha} = \begin{pmatrix} \overline{\rho} \\ \overline{\rho}\,\overline{v}_{\alpha} \\ \overline{\rho}\,\overline{e} \\ \overline{\rho}\,\overline{\phi} \end{pmatrix}$$



The Favre-averaged forces and sources are defined as follows



• The forces and sources are

$$\overline{F}_{\alpha} = \begin{pmatrix} 0 \\ \overline{\rho} g_{\alpha} \\ 0 \\ 0 \end{pmatrix}$$



 At large Reynolds numbers, the viscous stress terms and diffusive fluxes are assumed to be negligible compared to the Reynolds stress tensor and turbulent fluxes

A gradient diffusion approximation is usually used to model the turbulent stresses and fluxes

The gradient diffusion approximation is

$$\overline{\rho \phi_{\alpha}^{"} v_{j}^{"}} = \overline{\rho} \widetilde{\phi_{\alpha}^{"} v_{\beta}^{"}} = -\frac{\partial}{\partial x^{j}} \left(\frac{v_{t}}{\sigma \phi_{\alpha}} \overline{\rho} \phi_{\alpha} \right)$$

$$\tau_{ij} \equiv \overline{\rho v_{i}^{"} v_{j}^{"}} = \overline{\rho} \widetilde{v_{i}^{"} v_{j}^{"}}$$

$$= 2 \overline{\rho} \widetilde{E}^{"} \frac{\delta_{ij}}{3} - 2 \overline{\rho} v_{t} \left(\widetilde{S}_{kj} - \frac{\delta_{kj}}{3} \frac{\partial \widetilde{v}_{l}}{\partial x_{l}} \right)$$

$$\overline{\rho' v_{j}^{"}} = -\frac{\partial}{\partial x_{j}} \left(\frac{v_{t}}{\sigma \rho} \overline{\rho} \right)$$

• The eddy viscosity

$$v_t = C_{\mu} \left(\widetilde{E''} \right)^{\frac{m+2n}{n}} \left(\widetilde{Z''} \right)^{-\frac{1}{n}}$$

is determined by the solution of transport equations for two turbulence variables K (= E') and

$$\widetilde{Z''} \equiv C_Z \left(\widetilde{E''}\right)^m \left(\widetilde{\epsilon''}\right)^n$$

The turbulent kinetic energy equation is closed as follows

• The unclosed turbulent kinetic energy equation is

$$\frac{\partial}{\partial t} \left(\overline{\rho} \widetilde{E}'' \right) + \frac{\partial}{\partial x_j} \left(\overline{\rho} \widetilde{E}'' \widetilde{\nu}_j \right)$$

$$= \underbrace{\left(\overline{\rho} \overline{\nu}_i'' + \overline{\rho' \nu_i''} \right) g_i}_{\text{force production}} - \underbrace{\frac{\partial}{\partial x_j} \left(\frac{\overline{\rho \nu''^2 \nu_j''}}{2} + \overline{\rho' \nu_j''} - \overline{\nu}_i'' \overline{\sigma}_{ij}'' - \overline{\nu}_i'' \overline{\sigma}_{ij}''} \right)}_{\text{turbulentdiffusion}}$$

$$+ \underbrace{\widetilde{\nu}_i \frac{\partial}{\partial x_j} \left(\overline{\rho \nu}_i'' \nu_j'' \right)}_{\text{mean velocity production}} - \underbrace{\overline{\nu}_i'' \frac{\partial \overline{\rho}}{\partial x_i}}_{\text{pressure work}} + \underbrace{\overline{\rho' \frac{\partial \nu_j''}{\partial x_j}}_{\text{pressure dilatation}} - \underbrace{\overline{\sigma}_{ij}'' \frac{\partial \nu_i''}{\partial x_j}}_{\text{kinetic energy dissipation rate}}$$

 Use the gradient diffusion approximation to close the diffusion term and density flux, and (*Ma_t* is the turbulent Mach number)

$$\overline{p' \frac{\partial v''_i}{\partial x_j}} = \overline{p} \left(\alpha_2 \tau_{ij} \frac{\partial \widetilde{v}_i}{\partial x_j} + \alpha_3 M \alpha_t \widetilde{\epsilon''} \right) M \alpha_t^2$$
$$\overline{v''_i} = -\frac{\overline{\rho' v''_i}}{\overline{\rho}} = \frac{v_t}{\overline{\rho} \sigma_{\rho}} \frac{\partial \overline{\rho}}{\partial x^i}$$

The modeled turbulent kinetic energy dissipation rate transport equation is obtained as follows

 The turbulent kinetic energy dissipation rate equation is obtained by multiplying the turbulent kinetic energy equation by ε/K and a dimensionless constant for each term:

$$\frac{\partial}{\partial t} \left(\overline{\rho} \, \widetilde{\epsilon''} \right) + \frac{\partial}{\partial x_j} \left(\overline{\rho} \, \widetilde{\epsilon''} \, \widetilde{v}_j \right) \\ = \underbrace{C_{\epsilon 0} \, \frac{\widetilde{\epsilon''}}{\widetilde{E''}} \left(\overline{\rho} \, \overline{v''_i} + \overline{\rho' \, v''_i} \right) g_i}_{\mathcal{E}''} + \underbrace{C_{\epsilon 1} \, \frac{\widetilde{\epsilon''}}{\widetilde{E''}} \, \widetilde{v}_i \, \frac{\partial}{\partial x_j} \left(\overline{\rho} \, \overline{v''_i \, v''_j} \right)}_{\mathcal{E}''} \right)$$

force production



mean velocity production

$$-\underbrace{\frac{\partial}{\partial x_j} \left(\frac{\mu_t}{\sigma_{\epsilon}} \frac{\partial \widetilde{\epsilon''}}{\partial x^j} \right)}_{\mathbf{i}}$$

kinetic energy dissipation rate

turbulent diffusion



pressure work

pressure-dilatation

The modeled *Z* transport equation is obtained from the *K* and ε equations as follows



• Using the K and ε equations,

$$\frac{\partial}{\partial t} \left(\overline{\rho} \, \widetilde{Z}'' \right) + \frac{\partial}{\partial x_j} \left(\overline{\rho} \, \widetilde{Z}'' \, \widetilde{v}_j \right) = \overline{\rho} \left(\frac{\partial}{\partial t} + \widetilde{v}_j \, \frac{\partial}{\partial x_j} \right) \widetilde{Z}''$$

$$= \overline{\rho} \, \widetilde{Z}'' \left[\frac{m}{\widetilde{E}''} \left(\frac{\partial}{\partial t} + \widetilde{v}_j \, \frac{\partial}{\partial x_j} \right) \widetilde{E}'' + \frac{n}{\widetilde{\epsilon}''} \left(\frac{\partial}{\partial t} + \widetilde{v}_j \, \frac{\partial}{\partial x_j} \right) \widetilde{\epsilon}'' \right]$$

$$= m \, \frac{\widetilde{Z}''}{\widetilde{E}''} \left[\frac{\partial}{\partial t} \left(\overline{\rho} \, \widetilde{E}'' \right) + \frac{\partial}{\partial x_j} \left(\overline{\rho} \, \widetilde{E}'' \, \widetilde{v}_j \right) \right]$$

$$+ n \, \frac{\widetilde{Z}''}{\widetilde{\epsilon}''} \left[\frac{\partial}{\partial t} \left(\overline{\rho} \, \widetilde{\epsilon}'' \right) + \frac{\partial}{\partial x_j} \left(\overline{\rho} \, \widetilde{\epsilon}'' \, \widetilde{v}_j \right) \right]$$

$$= \frac{\widetilde{Z}''}{\widetilde{E}''} (m + n \, C_{\varepsilon_K}) \left[\frac{\partial}{\partial t} \left(\overline{\rho} \, \widetilde{E}'' \right) + \frac{\partial}{\partial x_j} \left(\overline{\rho} \, \widetilde{E}'' \, \widetilde{v}_j \right) \right]$$

The turbulent diffusion term is transformed as follows

Substituting

$$\widetilde{\epsilon''} = \left[\frac{\widetilde{Z''}}{C_Z(\widetilde{E''})^m}\right]^{1/n}$$

it follows that

$$\widetilde{Z}^{\prime\prime} \left[\frac{m}{\widetilde{E}^{\prime\prime}} \frac{\partial}{\partial x_{j}} \left(\frac{\mu_{t}}{\sigma_{k}} \frac{\partial \widetilde{E}^{\prime\prime}}{\partial x^{j}} \right) + \frac{n}{\widetilde{\epsilon}^{\prime\prime}} \frac{\partial}{\partial x_{j}} \left(\frac{\mu_{t}}{\sigma_{\epsilon}} \frac{\partial \widetilde{\epsilon}^{\prime\prime}}{\partial x^{j}} \right) \right]$$

$$= \frac{m\widetilde{Z}^{\prime\prime}}{\widetilde{E}^{\prime\prime}} \frac{\partial}{\partial x_{j}} \left(\frac{\mu_{t}}{\sigma_{k}} \frac{\partial \widetilde{E}^{\prime\prime\prime}}{\partial x^{j}} \right) + \frac{\partial}{\partial x_{j}} \left[\frac{\mu_{t}}{\sigma_{\epsilon}} \left(\frac{\partial \widetilde{Z}^{\prime\prime}}{\partial x^{j}} - \frac{m\widetilde{Z}^{\prime\prime}}{\widetilde{E}^{\prime\prime}} \frac{\partial \widetilde{E}^{\prime\prime\prime}}{\partial x^{j}} \right) \right]$$

$$+ \frac{\mu_{t}}{n\sigma_{\epsilon}} \left(\frac{\partial \widetilde{Z}^{\prime\prime}}{\partial x^{j}} - \frac{m\widetilde{Z}^{\prime\prime}}{\widetilde{E}^{\prime\prime}} \frac{\partial \widetilde{E}^{\prime\prime\prime}}{\partial x^{j}} \right) \left(\frac{1-n}{\widetilde{Z}^{\prime\prime}} \frac{\partial \widetilde{Z}^{\prime\prime}}{\partial x_{j}} - \frac{m}{\widetilde{E}^{\prime\prime\prime}} \frac{\partial \widetilde{E}^{\prime\prime\prime}}{\partial x_{j}} \right)$$

Finally, the modeled form of the Z transport equation is as follows



$$\frac{\partial}{\partial t} \left(\overrightarrow{p} \widetilde{Z''} \right) + \frac{\partial}{\partial x_j} \left(\overrightarrow{p} \widetilde{Z''} \widetilde{v}_j \right) = \overrightarrow{p} \left(\frac{\partial}{\partial t} + \widetilde{v}_j \frac{\partial}{\partial x_j} \right) \widetilde{Z''}$$

$$= \underbrace{C_{Z0} \frac{\widetilde{Z''}}{\widetilde{E''}} \left(\overrightarrow{p} \overline{v''_i} + \overrightarrow{p' v''_i} \right) g_i}_{\text{force production}} + \underbrace{C_{Z1} \frac{\widetilde{Z''}}{\widetilde{E''}} \widetilde{v}_i \frac{\partial}{\partial x_j} \left(\overrightarrow{p v''_i v''_j} \right)}_{\text{mean velocity production}} - \underbrace{C_{Z2} \ \overrightarrow{p} \frac{\widetilde{Z''} \widetilde{\epsilon''}}{\widetilde{E''}}}_{\text{true production rate}}$$

$$- \underbrace{\frac{\partial}{\partial x_j} \left[\left(\mu + \frac{\mu_t}{\sigma_{\epsilon}} \right) \frac{\partial \widetilde{Z''}}{\partial x^j} \right] - \frac{m \widetilde{Z''}}{\widetilde{E''}} \frac{\partial}{\partial x_j} \left(\frac{\mu_t}{\sigma_k} \frac{\partial \widetilde{E''}}{\partial x^j} \right) \right]}_{\text{turbulent diffusion}}$$

$$+ m \frac{\partial}{\partial x_j} \left(\frac{\mu_t}{\sigma_{\epsilon}} \frac{\widetilde{Z''}}{\widetilde{E''}} \frac{\partial \widetilde{E''}}{\partial x^j} \right) - \frac{\mu_t}{n \sigma_{\epsilon}} \left(\frac{\partial \widetilde{Z''}}{\partial x^j} - \frac{m \widetilde{Z''}}{\widetilde{E''}} \frac{\partial \widetilde{E''}}{\partial x^j} \right) \left(\frac{1-n}{\widetilde{Z''}} \frac{\partial \widetilde{Z''}}{\partial x_j} - \frac{m}{\widetilde{E''}} \frac{\partial \widetilde{E''}}{\partial x_j} \right)$$

turbulent diffusion



The coefficients in the modeled Z transport equation are obtained from those in the ε equation



$$\sigma_k = 1.0$$
 , $\sigma_{\epsilon} = 1.3$, $C_{\epsilon 1} = 1.44$, $C_{\epsilon 2} = 1.92$
 $C_{\epsilon 0} = C_{\epsilon 4} = 1.0$

• The coefficients in the Z equation are

$$C_{Z0} \equiv m + n C_{\epsilon 0} , \quad C_{Z1} \equiv m + n C_{\epsilon 1} , \quad C_{Z2} \equiv m + n C_{\epsilon 2}$$
$$C_{Z3} \equiv m + n C_{\epsilon 3} , \quad C_{Z4} \equiv m + n C_{\epsilon 4}$$

• Different choices of *m* and *n* yield different 2-equation models:

 $- \widetilde{E''} \cdot \widetilde{\epsilon''} \quad \text{with } m = 0 \text{ and } n = 1 \text{ (turbulent energy dissipation)} \\ - \widetilde{E''} \cdot \widetilde{\ell''} \quad \text{with } m = 3/2 \text{ and } n = -1 \text{ (turbulent lengthscale)} \\ - \widetilde{E''} \cdot \widetilde{\omega''} \quad \text{with } m = -1 \text{ and } n = 1 \text{ (turbulent frequency)} \\ - \widetilde{E''} \cdot \widetilde{\tau''} \quad \text{with } m = 1 \text{ and } n = -1 \text{ (turbulent timescale)}$



The *K-Z* model simplifies for several special types of turbulent flows, which can be used to tune the model coefficients



- Isotropic turbulence: power-law decaying solutions
 - Production terms proportional to τ_{ij} , the turbulent diffusion terms, and the mean velocity vanish
- Free shear flows (plane wake; mixing layer; plane, round, and radial jet): far-field, self-similar, statistically-stationary solutions
 - Solutions depend on the similarity variable $\eta = y/x$
- Turbulent boundary layers: power-law solutions in the logarithmic layer
 - Sufficiently far from the boundary, the eddy viscosity dominates the molecular viscosity and the advection terms are negligible

The *K-Z* model equations have power-law solutions for isotropic turbulence



$$\frac{dK}{dt} = -\epsilon \qquad \frac{dZ}{dt} = -C_{Z2} \frac{Z}{K} \epsilon$$

• The initial conditions are $K(0) = K_a$ nd $Z(0) = Z_0 = C_Z K_0^m \epsilon_0^n$

• The corresponding solutions are

$$\frac{K(t)}{K_0} = \left[1 + \left(\frac{C_{Z2}-m-n}{n}\right)\frac{\epsilon_0}{K_0}t\right]^{-n/(C_{Z2}-m-n)}$$
$$= \left[1 + \left(C_{\epsilon 2}-1\right)\frac{\epsilon_0}{K_0}t\right]^{-1/(C_{\epsilon 2}-1)}$$
$$\frac{Z(t)}{Z_0} = \left[\frac{K(t)}{K_0}\right]^{C_{Z2}} = \left[\frac{K(t)}{K_0}\right]^{m+nC_{\epsilon 2}}$$

• Experimentally, $K(t) \propto t^{1.34}$, which determines $C_{\epsilon 2}$ (or C_{Z2})

The *K-Z* model equations have similarity solutions for free shear flows



 The model equations reduce to (and are solved by transforming to the similarity variable)

$$\left(\overline{v}_{x} \frac{\partial}{\partial x} + \overline{v}_{y} \frac{\partial}{\partial y} \right) K = \tau_{xy} \frac{\partial \overline{v}_{x}}{\partial y} - \epsilon + \frac{1}{y^{r}} \frac{\partial}{\partial y} \left(y^{r} \frac{v_{t}}{\sigma_{k}} \frac{\partial K}{\partial y} \right)$$

$$\left(\overline{v}_{x} \frac{\partial}{\partial x} + \overline{v}_{y} \frac{\partial}{\partial y} \right) Z = C_{Z1} \frac{Z}{K} v_{t} \left(\frac{\partial \overline{v}_{i}}{\partial x_{j}} \right)^{2} - C_{Z2} \frac{Z}{K} \epsilon$$

$$\frac{1}{y^{r}} \frac{\partial}{\partial y} \left(y^{r} \frac{v_{t}}{\sigma_{\epsilon}} \frac{\partial Z}{\partial y} \right) + \frac{mZ}{Ky^{r}} \frac{\partial}{\partial y} \left(y^{r} \frac{v_{t}}{\sigma_{k}} \frac{\partial K}{\partial y} \right) - \frac{m}{y^{r}} \frac{\partial}{\partial y} \left(y^{r} \frac{v_{t}}{\sigma_{\epsilon}} \frac{Z}{K} \frac{\partial K}{\partial y} \right)$$

$$+ \frac{v_{t}}{n\sigma_{\epsilon}} \left(\frac{\partial Z}{\partial y} - \frac{mZ}{K} \frac{\partial K}{\partial y} \right) \left(\frac{1-n}{Z} \frac{\partial Z}{\partial y} - \frac{m}{K} \frac{\partial K}{\partial y} \right)$$

where r = 1 corresponds to a round jet and r = 0 otherwise, and the shear stress is

The *K-Z* model equations have similarity solutions for the mixing layer



• The solutions have the form

$$\overline{v}_{x}(x,y) = \Delta v \,\overline{v}_{x}(\eta)$$
$$K(x,y) = (\Delta v)^{2} K(\eta)$$
$$Z(x,y) = C_{Z} (\Delta v)^{2m} K(\eta)^{m} \left[\frac{(\Delta v)^{3}}{x}\right]^{n} \epsilon(\eta)^{n}$$

where $v = v_1 - v_2$ is the velocity difference between the two streams

The K-Z model equations have solutions consistent with the law-of-the-wall in bounded flows



$$\begin{aligned} \frac{\partial}{\partial y} \left(\mu_t \frac{\partial \overline{v}_x}{\partial y} \right) &= 0 \\ \mu_t \left(\frac{\partial \overline{v}_x}{\partial y} \right)^2 + \frac{\partial}{\partial y} \left(\frac{\mu_t}{\sigma_K} \frac{\partial K}{\partial y} \right) - \rho \epsilon &= 0 \\ C_{Z1} \frac{Z}{K} \mu_t \left(\frac{\partial \overline{v}_x}{\partial y} \right)^2 - C_{Z2} \rho \frac{Z}{K} \epsilon + \frac{\partial}{\partial y} \left(\frac{\mu_t}{\sigma_\epsilon} \frac{\partial Z}{\partial y} \right) \\ &+ \frac{mZ}{K} \frac{\partial}{\partial y} \left(\frac{\mu_t}{\sigma_k} \frac{\partial K}{\partial y} \right) - m \frac{\partial}{\partial y} \left(\frac{\mu_t}{\sigma_\epsilon} \frac{Z}{K} \frac{\partial K}{\partial y} \right) \\ &+ \frac{\mu_t}{n\sigma_\epsilon} \left(\frac{\partial Z}{\partial y} - \frac{mZ}{K} \frac{\partial K}{\partial y} \right) \left(\frac{1-n}{Z} \frac{\partial Z}{\partial y} - \frac{m}{K} \frac{\partial K}{\partial y} \right) = 0 \end{aligned}$$

• The solutions have the form (where v_{τ} is the friction velocity, κ is the von Kármán constant, and C, D, C_Z are constants)

$$\overline{v}_x = \frac{v_{\tau}}{\kappa} \log y + C \quad , \quad K = Dv_{\tau}^2 \quad , \quad Z = C_Z D^m v_{\tau}^{2m+3n} \left(\frac{1}{\kappa y}\right)_{\text{Oleg Schilling}}^n$$

Application to asymptotically self-similar Rayleigh-Taylor mixing



• The turbulence production term is of the form

$$P_Z = C_{Z1} \frac{\widetilde{Z''}}{\widetilde{E''}} \tau_{ij} \frac{\partial \widetilde{v}_i}{\partial x_j}$$

 Assume that at sufficiently late times, the scaling of the mixing layer width is

$$h(t) = \alpha A t g t^2$$

and that turbulence variables are proportional to this lengthscale and the corresponding velocity scale

• Then, K, ε , and Z are

$$\widetilde{E''} = \frac{\widetilde{v''^2}}{2} \propto \left(\frac{dh}{dt}\right)^2 \propto 4(\alpha Atg)^2 t^2 \qquad \widetilde{\epsilon''} = \frac{\partial \widetilde{E_k''}}{\partial t} \propto 8(\alpha Atg)^2 t$$
$$\widetilde{Z''} = C_Z \left(\widetilde{E''}\right)^m \left(\widetilde{\epsilon''}\right)^n \propto (\alpha Atg)^{2m+2n} t^{2m+n}$$

In Rayleigh-Taylor mixing the eddy viscosity and Reynolds stress tensor scale as follows



• The eddy viscosity scales as

$$v_t = \left(\widetilde{E''}\right)^{\frac{m+2n}{n}} \left(\widetilde{Z''}\right)^{-\frac{1}{n}} \propto (\alpha A t g)^2 t^3$$

The Reynolds stress scales as

$$\tau_{ij} = 2 \overline{\rho} \widetilde{E}^{''} \frac{\delta_{ij}}{d} - 2 \overline{\rho} v_t \left(\widetilde{S}_{ij} - \frac{\delta_{ij}}{d} \frac{\partial \widetilde{v}_k}{\partial x_k} \right)$$

$$\propto 2 \overline{\rho} (\alpha A t g)^2 t^2 \left[\frac{4}{d} \delta_{ij} - \left(\widetilde{S}_{ij} - \frac{\delta_{ij}}{d} \frac{\partial \widetilde{v}_k}{\partial x_k} \right) t \right]$$

• Therefore, if the Favre-averaged strain-rate tensor dimensionally scales as (q_{ii} is dimensionless)

$$\widetilde{S}_{ij} = \frac{1}{2} \left(\frac{\partial \widetilde{v}_i}{\partial x_j} + \frac{\partial \widetilde{v}_j}{\partial x_i} \right) \propto q_{ij} \frac{1}{h(t)} \frac{dh(t)}{dt} \propto \frac{1}{t}$$

then $\tau_{ij} \propto 2 \overline{\rho} (\alpha A t g)^2 t^2 \left(\frac{5}{d} \delta_{ij} - q_{ij} \right)$ and

$$P_Z \propto (\alpha A t g)^{2(m+n)} t^{2m+n-1} \overline{\rho} \left(\frac{5}{d} \delta_{ij} - q_{ij}\right) q_{ij}$$

Conclusions



- The methodology presented here provides a systematic and selfconsistent approach to the derivation of 2-equation turbulent transport models
 - This provides an improved / transport equation
 - Also provides a consistent expression for the diffusion and cross diffusion terms, which are important in many flow (e.g., near a boundary)
- Several canonical turbulent flows can be used to reduce the model equations and specify model parameters before application to interfacial-instability induced turbulence
- The general Z equation is consistent with the t² scaling of the mixing layer width
- Both an ω and a τ equation were derived as alternatives to the ε and *l* equation
 - $-\tau$ may be a better physical variable than ε and I

Work in progress



- Completion of solutions for canonical turbulent flows
- Completion of solutions for Rayleigh-Taylor instability-induced turbulence
- Commencement of examination of model parameters and forms of modeled terms using high-resolution DNS data
- Eventually, application to Richtmyer-Meshkov instability-induced turbulence